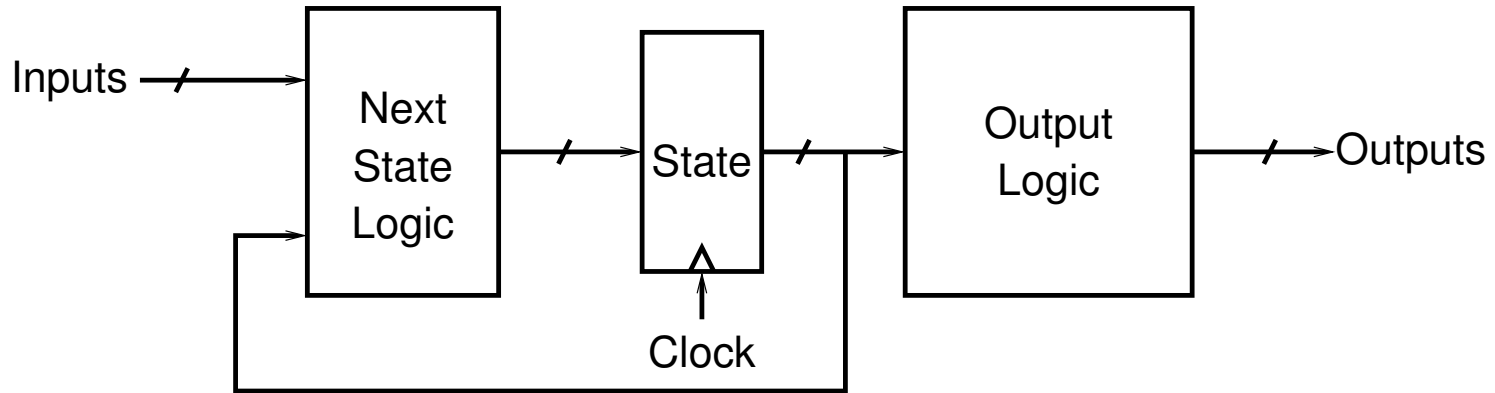
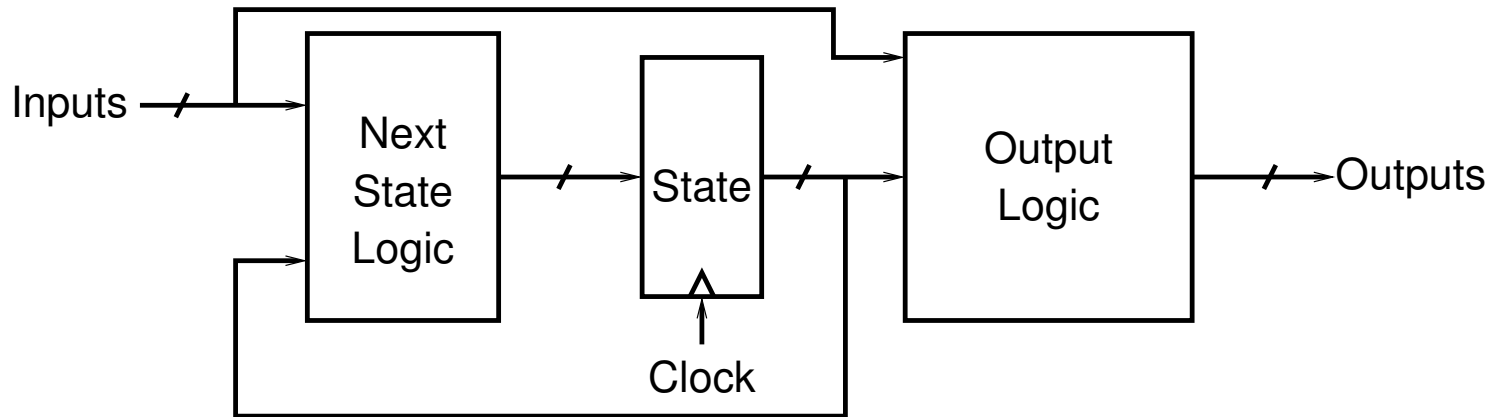


ASM

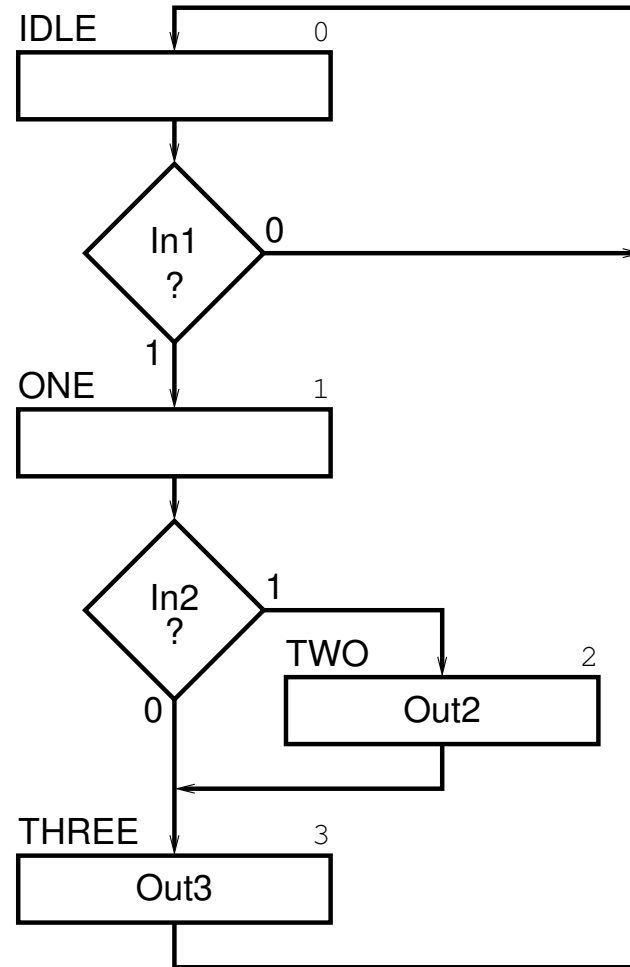
Moore State Machine



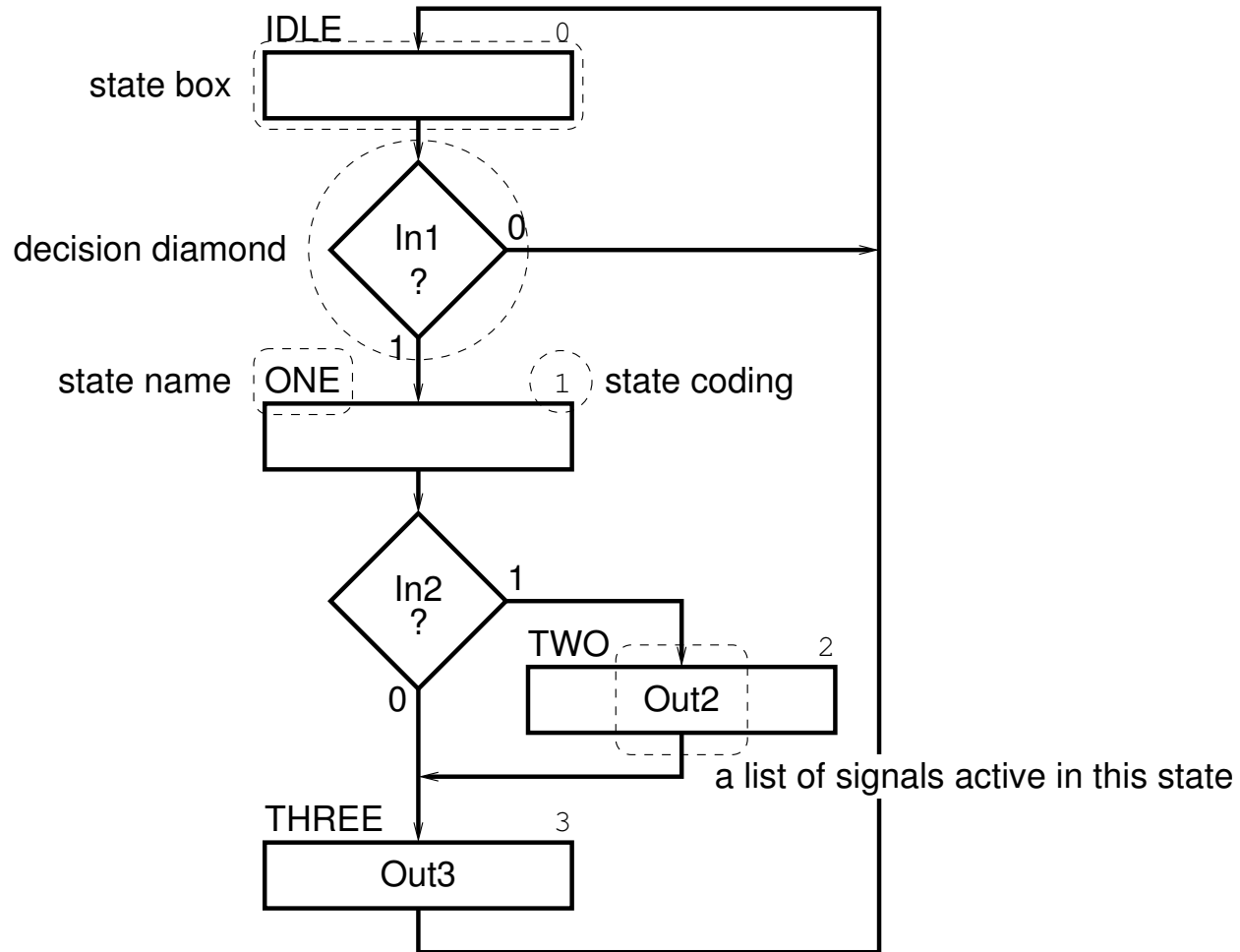
Mealy State Machine



ASM1 – Moore Machine



ASM1 – Moore Machine



ASM1^a

```
// ----- state declaration -----  
logic [1:0] state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)      state <= 0;  
  else  
    case (state)  
      0:      if (In1)  state <= 1;  
      1:      if (In2)  state <= 2;  
              else     state <= 3;  
      2:      state <= 3;  
      3:      state <= 0;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
  assign Out2 = (state == 2);  
  assign Out3 = (state == 3);
```

ASM1^b – using state names and enumerated types¹

```
// ----- state declaration -----  
enum logic [1:0] { IDLE=0, ONE=1, TWO=2, THREE=3 } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    case (state)  
      IDLE : if (In1)  state <= ONE;  
      ONE  : if (In2)  state <= TWO;  
            else      state <= THREE;  
      TWO  :          state <= THREE;  
      THREE:          state <= IDLE;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
  assign Out2 = (state == TWO);  
  assign Out3 = (state == THREE);
```

¹a synthesis program may re-allocate the states
(the default state assignments shown here are optional)

ASM1^c – using a procedural block to infer combinational logic

```
// ----- state declaration -----  
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    case (state)  
      IDLE : if (In1)  state <= ONE;  
      ONE  : if (In2)  state <= TWO;  
            else      state <= THREE;  
      TWO  :           state <= THREE;  
      THREE:           state <= IDLE;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
always_comb  
  begin  
    Out2 = (state == TWO);  
    Out3 = (state == THREE);  
  end
```

ASM1^d – using typedef

```
// ----- state declaration -----
typedef enum logic [1:0] { IDLE, ONE, TWO, THREE } state_t;
state_t state;
// ----- state + next state logic -----
always_ff @(posedge Clock, negedge nReset)
    if (!nReset)          state <= IDLE;
    else
        case (state)
            IDLE : if (In1) state <= ONE;
            ONE  : if (In2) state <= TWO;
                   else    state <= THREE;
            TWO  :          state <= THREE;
            THREE:          state <= IDLE;
        endcase

// ----- output logic -----
logic Out2, Out3;
always_comb
    begin
        Out2 = (state == TWO);
        Out3 = (state == THREE);
    end
```

ASM1^e – using **if else** instead of **case**

```
// ----- state declaration -----  
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    if ((state == IDLE) && In1)  
      state <= ONE;  
    else if ((state == ONE) && In2)  
      state <= TWO;  
    else if ((state == ONE) || (state == TWO))  
      state <= THREE;  
    else  
      state <= IDLE;  
// ----- output logic -----  
logic Out2, Out3;  
always_comb  
  begin  
    Out2 = (state == TWO);  
    Out3 = (state == THREE);  
  end
```


ASM1^f – multiple assignment (default and override)

```
// ----- state declaration -----
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;

// ----- state + next state logic vlsi02.tex-----
always_ff @(posedge Clock, negedge nReset)
  if (!nReset)          state <= IDLE;
  else
    case (state)
      IDLE : if (In1)  state <= ONE;
      ONE  : if (In2)  state <= TWO;
             else    state <= THREE;
      TWO  :           state <= THREE;
      THREE:           state <= IDLE;
    endcase

// ----- output logic -----
logic Out2, Out3;
always_comb
  begin
    Out2 = 0; Out3 = 0;           // <- default values assigned here

    if ( state == TWO )  Out2 = 1; // <- only non-default values
    if ( state == THREE ) Out3 = 1; //   assigned here
  end
```

ASM1^g – multiple assignment (default and override) with case

```
// ----- state declaration -----  
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    case (state)  
      IDLE : if (In1)  state <= ONE;  
      ONE  : if (In2)  state <= TWO;  
            else      state <= THREE;  
      TWO  :           state <= THREE;  
      THREE:           state <= IDLE;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
always_comb  
  begin  
    Out2 = 0; Out3 = 0;           // <- default values assigned here  
    case (state)  TWO   : Out2 = 1; // <- only non-default values  
                  THREE : Out3 = 1; // assigned here  
    endcase  
  end
```

ASM1^h – using a single procedural block *(This style is not advised for novices!)*²

// Caution: infers registered outputs for Out2 and Out3

```
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;
logic Out2, Out3;

always_ff @(posedge Clock, negedge nReset)
  if (!nReset) begin state <= IDLE;
                                     Out2 <= 0; Out3 <= 0; end

  else
    begin
      Out2 <= (state == ONE) && In2;
      Out3 <= (state == ONE) && !In2 || (state == TWO);
      case (state)
        IDLE : if (In1) state <= ONE;
        ONE  : if (In2) state <= TWO;
              else state <= THREE;
        TWO  : state <= THREE;
        THREE: state <= IDLE;
      endcase
    end
```

²here we predict in one state, the outputs that we need in the next state
– it is hard to see which output is associated with which state ∴ error prone

ASM1ⁱ – using a single procedural block *(This style is not advised for novices!)*³

// Caution: infers registered outputs for Out2 and Out3

```
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;
logic Out2, Out3;

always_ff @(posedge Clock, negedge nReset)
  if (!nReset) begin state <= IDLE;
                Out2 <= 0; Out3 <= 0; end

  else
    case (state)
      IDLE : if (In1) begin state <= ONE;
                Out2 <= 0; Out3 <= 0; end
      ONE  : if (In2) begin state <= TWO;
                Out2 <= 1; Out3 <= 0; end
                else begin state <= THREE;
                Out2 <= 0; Out3 <= 1; end
      TWO  : begin state <= THREE;
                Out2 <= 0; Out3 <= 1; end
      THREE: begin state <= IDLE;
                Out2 <= 0; Out3 <= 0; end
    endcase
```

³here the outputs are clearly associated with the appropriate states
– includes duplicated sections of code ∴ error prone

ASM1^j – using a single procedural block *(This style is not advised for novices!)*⁴

// Caution: infers registered outputs for Out2 and Out3

```
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;
logic Out2, Out3;

always_ff @(posedge Clock, negedge nReset)
  if (!nReset) begin state <= IDLE;
                Out2 <= 0; Out3 <= 0; end

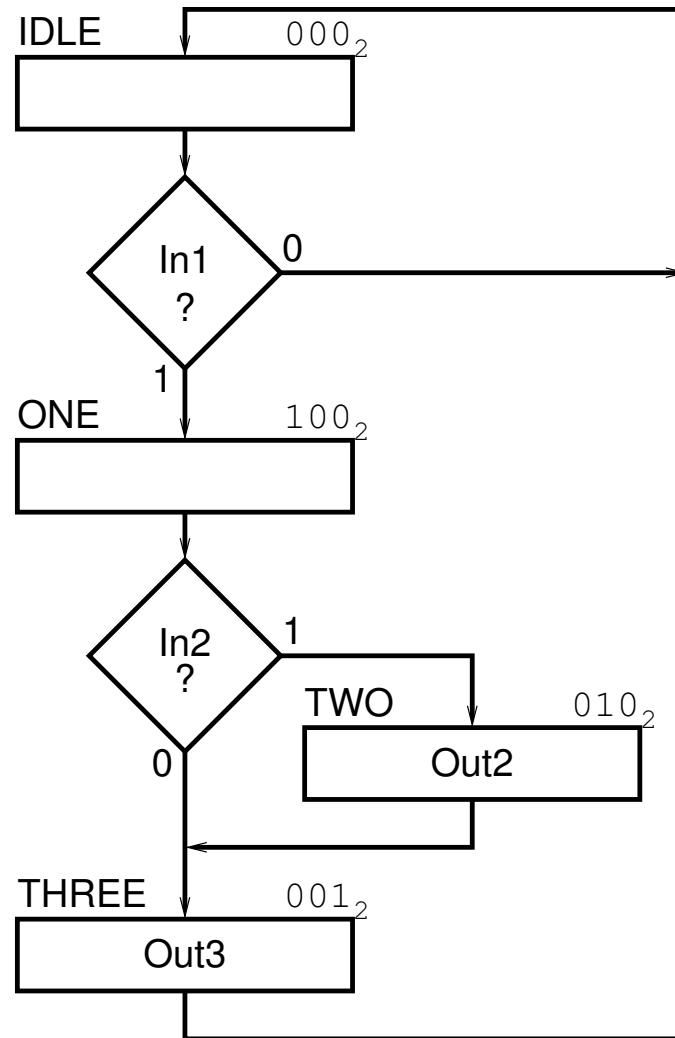
  else
    if ((state == IDLE) && In1)
      begin state <= ONE;
            Out2 <= 0; Out3 <= 0; end
    else if ((state == ONE) && In2)
      begin state <= TWO;
            Out2 <= 1; Out3 <= 0; end
    else if ((state == ONE) || (state == TWO))
      begin state <= THREE;
            Out2 <= 0; Out3 <= 1; end

    else
      begin state <= IDLE;
            Out2 <= 0; Out3 <= 0; end
```

⁴here **if else** structure is used to avoid duplication of state THREE code
– the resulting code is not easy to follow ∴ error prone

ASM1* – Moore Machine

(with optimized state coding)



ASM1^k – using a single procedural block

(with optimized state coding)⁵

```
typedef enum logic [2:0]
  { IDLE=3'b000, ONE=3'b100, TWO=3'b010, THREE=3'b001 } state_t;
logic state, Out2, Out3;

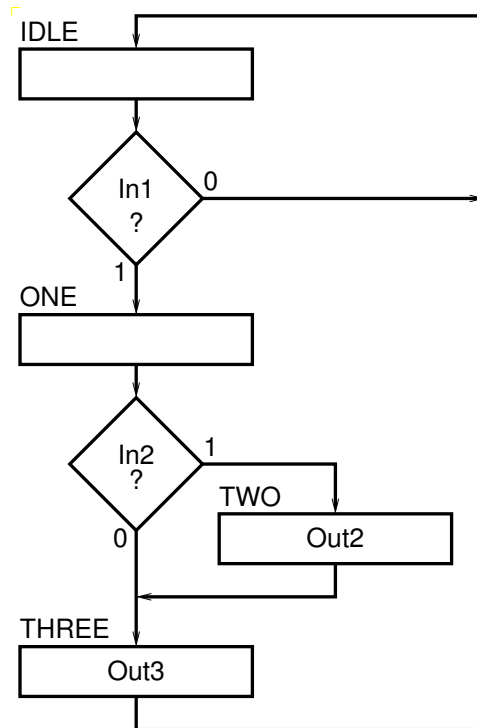
always_ff @(posedge Clock, negedge nReset)
  if (!nReset) {state, Out2, Out3} <= IDLE;
  else
    case ({state, Out2, Out3})
      IDLE : if (In1) {state, Out2, Out3} <= ONE;
             else {state, Out2, Out3} <= IDLE;
      ONE  : if (In2) {state, Out2, Out3} <= TWO;
             else {state, Out2, Out3} <= THREE;
      TWO  : {state, Out2, Out3} <= THREE;
      THREE: {state, Out2, Out3} <= IDLE;
    endcase
```

⁵here the outputs are considered to be part of the state

- **typedef** is used to define state_t but state_t is never used
 - only the state names are used
 - state is a single bit logic variable
- the resulting code is concise but is it easy to follow?

ASM - Single Procedural Block Approach?

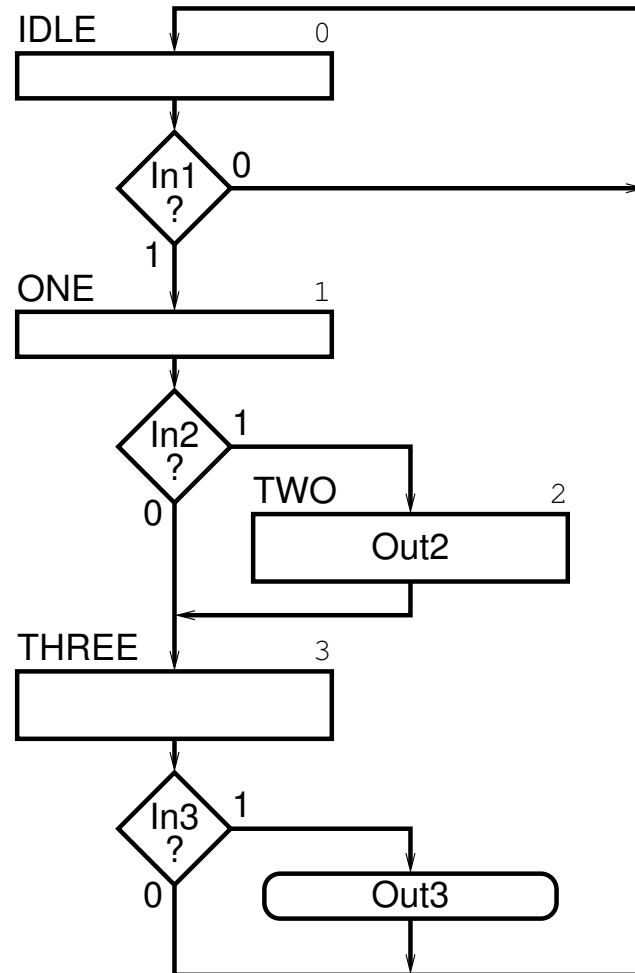
Some ASMs lend themselves to implementation as a single procedural block ...



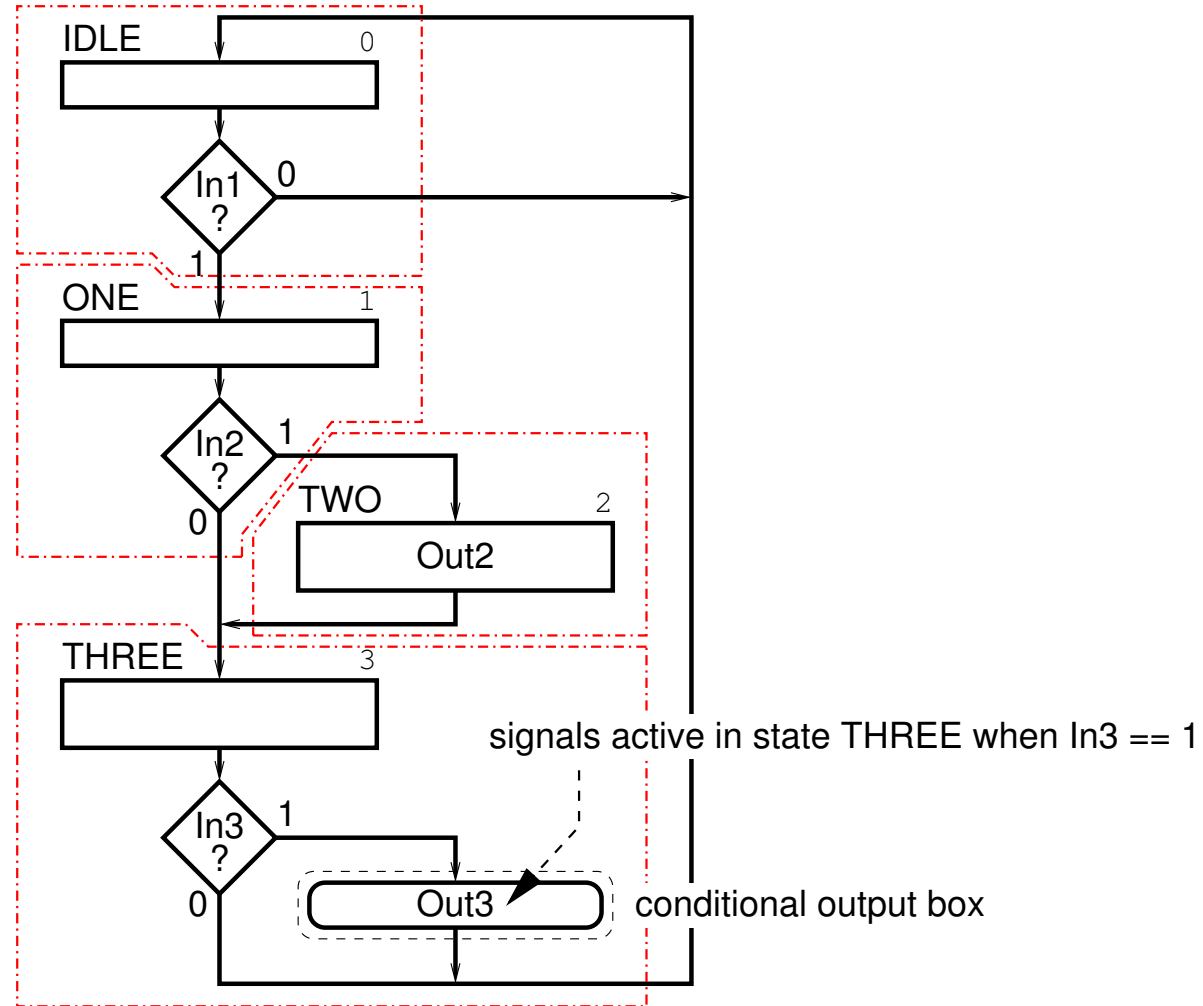
State + Next State Logic	Output Logic	
<code>always_ff</code>	<code>assign</code>	✓
<code>always_ff</code>	<code>always_comb</code>	✓
<code>always_ff</code>		✗

This is **NOT** one of them.

ASM2 – Mealy Machine



ASM2 – Mealy Machine



ASM2^a

```
// ----- state declaration -----  
logic [1:0] state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= 0;  
  else  
    case (state)  
      0:      if (In1)  state <= 1;  
      1:      if (In2)  state <= 2;  
              else     state <= 3;  
      2:      state <= 3;  
      3:      state <= 0;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
  assign Out2 = (state == 2);  
  assign Out3 = (state == 3) && In3;
```

ASM2^b – using state names

```
// ----- state declaration -----  
enum logic [1:0] { IDLE=0, ONE=1, TWO=2, THREE=3 } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    case (state)  
      IDLE : if (In1)  state <= ONE;  
      ONE  : if (In2)  state <= TWO;  
            else      state <= THREE;  
      TWO  :           state <= THREE;  
      THREE:           state <= IDLE;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
  assign Out2 = (state == TWO);  
  assign Out3 = (state == THREE) && In3;
```

ASM2^c – using a procedural block to infer combinational logic

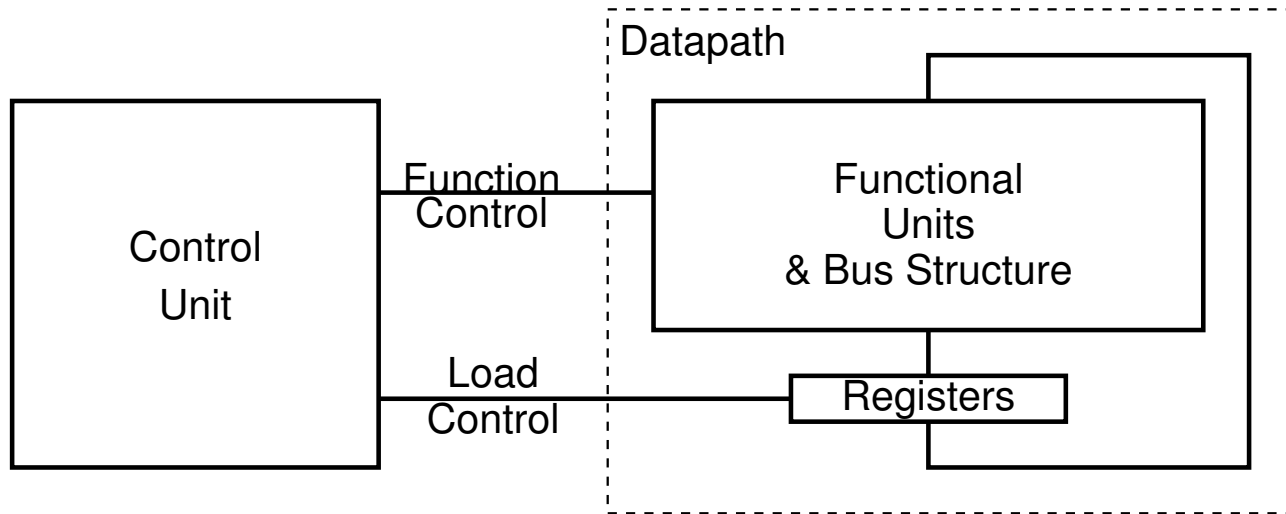
```
// ----- state declaration -----  
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;  
  
// ----- state + next state logic -----  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          state <= IDLE;  
  else  
    case (state)  
      IDLE : if (In1)  state <= ONE;  
      ONE  : if (In2)  state <= TWO;  
            else      state <= THREE;  
      TWO  :           state <= THREE;  
      THREE:           state <= IDLE;  
    endcase  
  
// ----- output logic -----  
logic Out2, Out3;  
always_comb  
  begin  
    Out2 = (state == TWO);  
    Out3 = ((state == THREE) && In3);  
  end
```

ASM2^h single procedural block not possible⁶

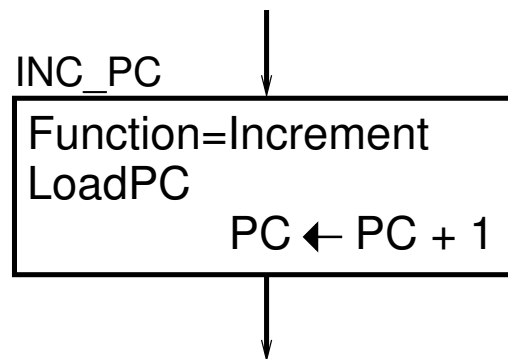
```
// ----- state block generates Out2 -----  
enum logic [1:0] { IDLE, ONE, TWO, THREE } state;  
logic Out2;  
  
always_ff @(posedge Clock, negedge nReset)  
  if (!nReset)          begin state <= IDLE; Out2 <= 0; end  
  else  
    begin  
      Out2 <= (state == ONE) && In2;  
      case (state)  
        IDLE : if (In1)      state <= ONE;  
        ONE  : if (In2)      state <= TWO;  
              else          state <= THREE;  
        TWO  :                state <= THREE;  
        THREE:                state <= IDLE;  
      endcase  
    end  
  
// ----- output logic generates Out3 -----  
logic Out3;  
  assign Out3 = (state == THREE) && In3;
```

⁶n.b. *single procedural block solution not possible for Mealy machine since we have conditional outputs.*

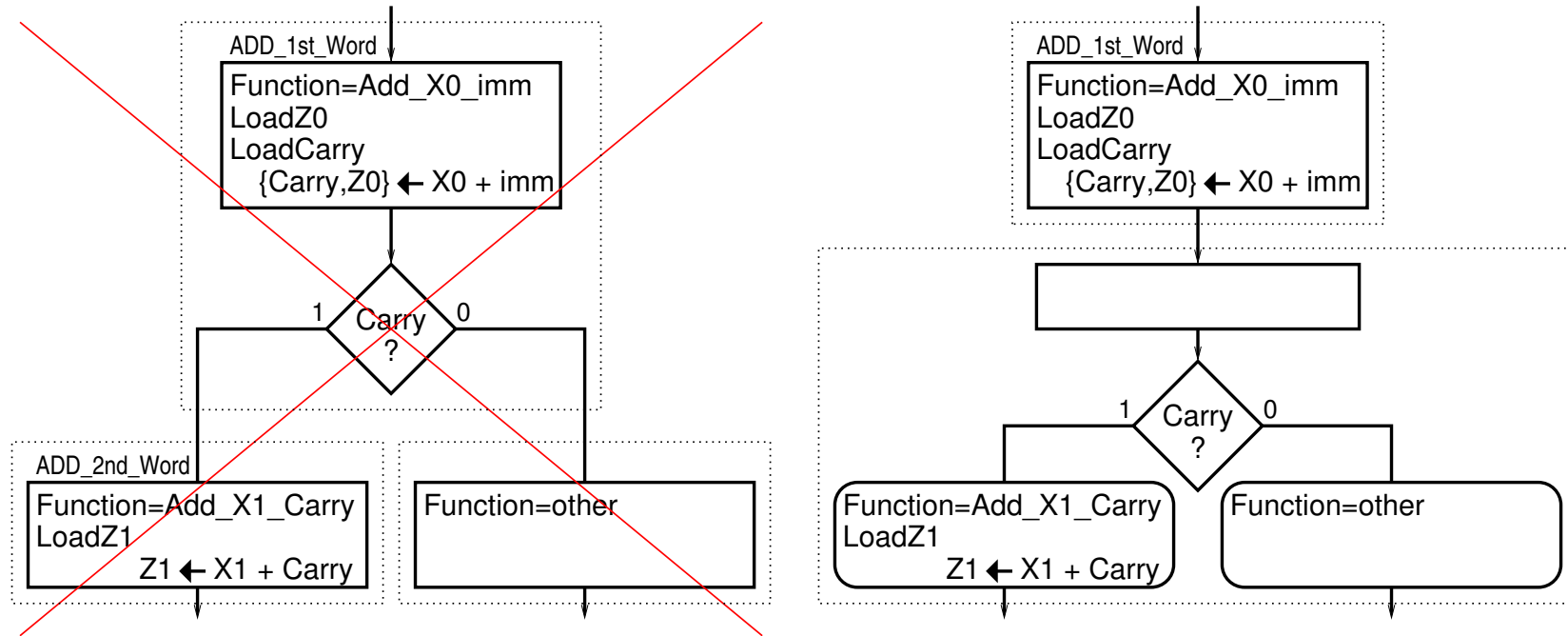
Datapath Control



For successful update we must simultaneously control function and register update:



Datapath Control



Since datapath registers are updated at the end of the clock cycle, we must wait until the next state before testing new values⁷.

⁷in some cases it may be better to test values at the input to a register, e.g. if (nextCarry == 1)...